SRH1 Series Single-Phase, Integrated Heatsink Type SSR

Single-Phase, Integrated Heatsink Type SSR

Features

• High heat dissipation efficiency with ceramic PCB and integrated heatsink

- Input Indicator (green LED)
- DIN rail mount or panel mount installation
- [Voltage input type] Zero cross turn-on, random turn-on models available
- [Current input type] Phase control and cycle control possible
 - Phase control (power equality division/phase equality division)
 - Cycle control (fixed cycle/variable cycle)

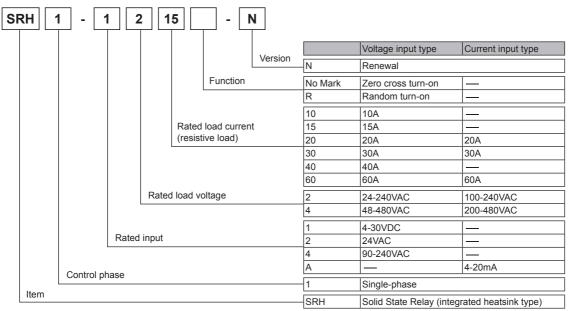




current

Please read "Safety considerations" in operation manual before using.

Ordering Information



XThis ordering information is only for reference. For ordering a specific model, check the ordering information of the model.

XFor more information about models, refer to the [B-16 page for the voltage input type]

B-22 page for the current input type

(A) Photoelectric Sensors

Line-up

(C) Door/Area Sensors

(D) Proximity Sensors

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Powe Controllers

(M) Tacho / Speed / Pulse Meters

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

(R) Graphic/ Logic Panels

I-15 **Autonics**

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

■ Model

Model	Rated input voltage	Rated load voltage	Rated input current	Function
SRH1-1210-N	4-30VDC			
SRH1-2210-N	24VAC	10A		
SRH1-4210-N	90-240VAC			
SRH1-1215-N	4-30VDC			
SRH1-2215-N	24VAC	15A		
SRH1-4215-N	90-240VAC			
SRH1-1220-N	4-30VDC			
SRH1-2220-N	24VAC	20A		
SRH1-4220-N	90-240VAC		24 240 (4.0	7 4
SRH1-1230-N	4-30VDC		24-240VAC	Zero cross turn-on
SRH1-2230-N	24VAC	30A		
SRH1-4230-N	90-240VAC			
SRH1-1240-N	4-30VDC			
SRH1-2240-N	24VAC	40A		
SRH1-4240-N	90-240VAC			
SRH1-1260-N	4-30VDC			
SRH1-2260-N	24VAC	60A		
SRH1-4260-N	90-240VAC			
SRH1-1410-N	4.20\/DC			Zero cross turn-on
SRH1-1410R-N	4-30VDC	10A		Random turn-on
SRH1-2410-N	24VAC			Zero cross turn-on
SRH1-1415-N	4.20\/DC			Zero cross turn-on
SRH1-1415R-N	4-30VDC	15A		Random turn-on
SRH1-2415-N	24VAC			Zero cross turn-on
SRH1-1420-N	4.00\/D0			Zero cross turn-on
SRH1-1420R-N	4-30VDC	20A		Random turn-on
SRH1-2420-N	24VAC		40, 400) (4.0	Zero cross turn-on
SRH1-1430-N	4.00\/D0		48-480VAC	Zero cross turn-on
SRH1-1430R-N	4-30VDC	30A		Random turn-on
SRH1-2430-N	24VAC			Zero cross turn-on
SRH1-1440-N	4 30VDC			Zero cross turn-on
SRH1-1440R-N	4-30VDC	40A		Random turn-on
SRH1-2440-N	24VAC			Zero cross turn-on
SRH1-1460-N	4 20VDC			Zero cross turn-on
SRH1-1460R-N	4-30VDC	60A		Random turn-on
SRH1-2460-N	24VAC			Zero cross turn-on

Specifications

○ Input

Rated inp	put voltage range	4-30VDC	24VACrms∼ (50/60Hz)	90-240VACrms \sim (50/60Hz)
Allowable	e input voltage range	4-32VDC==	19-30VACrms∼ (50/60Hz)	85-264VACrms~ (50/60Hz)
Max. inpu	ut current	18mA	15mArms (24VACrms~)	18mArms (240VACrms∼)
Pick-up v	/oltage	Min. 4VDC==	Min. 19VACrms∼	Min. 85VACrms~
Drop-out	voltage	Max. 1VDC==	Max. 4VACrms∼	Max. 10VACrms∼
Turn-on	Zero cross turn-on	Max. 0.5 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms
time	Random turn-on	Max. 1ms		_
Turn-off t	time	Max. 0.5 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms

I-16 Autonics

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

Output

Rated load voltage range 24-240VACrms~ (50/60Hz)							
Allowable load	d voltage range	24-264VACrms^	~ (50/60Hz)				
Rated load current	Resistive load (AC-51) ^{×1}	10Arms	15Arms	20Arms	30Arms	40Arms	60Arms
Min. load curre	ent	0.15Arms	0.15Arms	0.2Arms	0.5Arms	0.5Arms	0.5Arms
Max. 1 cycle s (60Hz)	surge current	160A	160A	250A	400A	500A	1000A
Max. non-repe current (I ² t, t=8		130A ² s	130A ² s	300A ² s	910A ² s	1000A ² s	4000A ² s
Peak voltage	(non-repetitive)	600V					
Leakage curre	ent (Ta=25°C)	Max. 10mArms (240VAC~/60H	z)			
Output on voltage drop [Vpk] Max. 1.6V							
Static off state	Static off state dv/dt 500V/µs						
Rated load vo	Itage range	48-480VACrms	√ (50/60Hz)				
Allowable load	d voltage range	48-528VACrms^	~ (50/60Hz)				
Rated load current	Resistive load (AC-51) ^{×1}	10Arms	15Arms	20Arms	30Arms	40Arms	60Arms
Min. load curre	ent	0.5Arms	0.5Arms	0.5Arms	0.5Arms	0.5Arms	0.5Arms
Max. 1 cycle surge current (60Hz)		300A	300A	300A	500A	500A	1000A
Max. non-repetitive surge current (I ² t, t=8.3ms)		350A ² s	350A ² s	350A ² s	1000A ² s	1000A ² s	4000A ² s
Peak voltage ((non-repetitive)	1200V (zero cros	ss turn-on), 100	0V (random turn-o	on)	•	
Leakage curre	ent (Ta=25°C)	Max. 10mArms (480VAC~/60H	z)			
	age drop [Vpk]	Max. 1.6V					
(max. load cur	Territ)						

X1: AC-51 is utilization category at IEC60947-4-3.

General specifications

	•				
Dielectric strength (Vrms)		2500VAC 50/60Hz 1 min (input-output, input/output-case)			
Insulation resistance		over 100MΩ (at 500VDC megger) (input-output, input/output-case)			
Indicator		Input indicator: green LED			
\ (ila == 4i = =	Mechanical	0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour			
Vibration	Malfunction	0.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 min			
Oh a ala	Mechanical	300m/s² (approx. 30G) in each X, Y, Z direction for 3 times	[],		
Shock	Malfunction	100m/s² (approx. 30G) in each X, Y, Z direction for 3 times			
Environment Ambient temp.		-30 to 80°C (in case of the rated input voltage 90-240VAC∼: -20 to 70°C), storage: -30 to 100°C (The rated load current capacity is different depending on ambient temperature. Refer to ■ SSR Derating Curve'.)			
	Ambient humi.	45 to 85%RH, storage: 45 to 85%RH			
Input terminal connection		Min. 1×0.5mm ² (1×AWG20), max. 1×1.5mm ² (1×AWG16) or 2×1.5mm ² (2×AWG16)	1 -		
Output terminal connection		Rated load current 10A/15A/20A : Min. 1×0.75mm² (1×AWG18), max. 1×4mm² (1×AWG12) or 2×2.5mm² (2×AWG14) Rated load current 30A/40A/60A : Min. 1×1.5mm² (1×AWG16), max. 1×16mm² (1×AWG6) or 2×6mm² (2×AWG10) **Use wires compliant with load current capacity to connect to the terminal.	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
Input terminal	I fixed torque	0.75 to 0.95N·m	H		
Output terminal fixed torque		Rated load current 10A/15A/20A: 1.0 to 1.35N·m Rated load current 30A/40A/60A: 1.6 to 2.2N·m			
Approval		(€ c) U (2) ∋)	H		
Weight ^{×1}		 Rated load current 10A/15A/20A: approx. 298g (approx. 225g) Rated load current 30A/40A: approx. 500g (approx. 410g) Rated load current 60A: approx. 770g (approx. 680g) 			

 $[\]ensuremath{\mathbb{X}}$ 1: The weight includes packaging. The weight in parenthesis is for unit only.

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature

(I) SSRs / Power Controllers

(J) Counters

K)

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

> O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Controllers

(R)
Graphic/
Logic
Panels

Logic Panels (S)

S) ield letwork levices

(T) Software

Autonics I-17

 $[\]times \mbox{Environment}$ resistance is rated at no freezing or condensation.

XFor wiring the terminal, round terminal must be used.

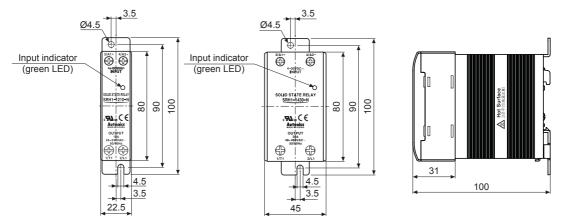
■ Dimensions & Mounting

O Dimensions

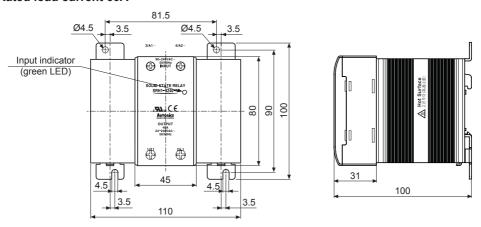
(unit: mm)

• Rated load current 10A/15A/20A

• Rated load current 30A/40A

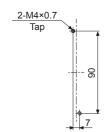


• Rated load current 60A

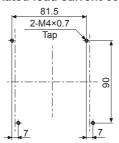


O Hole cut-out for mounting on panel

• Rated load current 10A/15A/20A/30A/40A



• Rated load current 60A



XScrew tightening torque for mounting: 1.8 to 2.5N⋅m

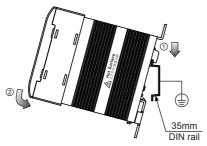
I-18 Autonics

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

(unit: mm)

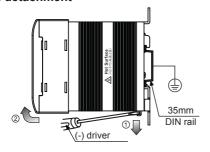
O DIN rail mounting

DIN rail attachment

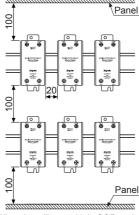


XDIN rail must be grounded.

DIN rail detachment



Spacing



*When installing multiple SSRs, please keep space between SSRs for heat radiation.

When installing SSRs horizontally (input part and output part on the same height), please supply less than 50% of the rated load current.

High temperature caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink.

Failure to follow this instruction may result in a burn due to the high temperature.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

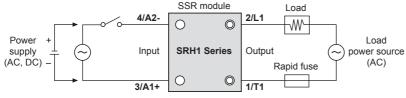


(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers (R) Graphic/ Logic Panels

Connections



XUse terminals of size specified below.

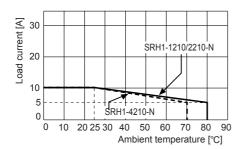
//								
Terminal type		Input	Output					
Rated load current		10A, 15A, 20A, 30A, 40A, 60A	10A, 15A, 20A	30A, 40A, 60A				
= () ta b	а	Min. 3.5mm	Min. 4.0mm	Min. 5.0mm				
<round></round>	b	Max. 7.0mm	Max. 9.0mm	Max. 12.0mm				

I-19 **Autonics**

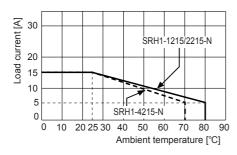
SRH1 Series

■ SSR Derating Curve

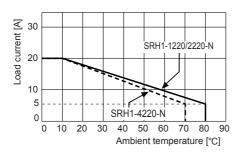
© SRH1-1210/2210/4210-N



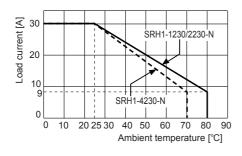
© SRH1-1215/2215/4215-N



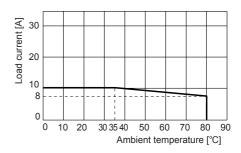
© SRH1-1220/2220/4220-N



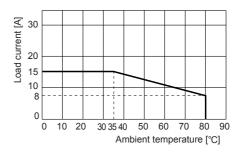
© SRH1-1230/2230/4230-N



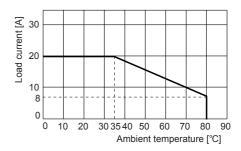
© SRH1-1410/1410R/2410-N



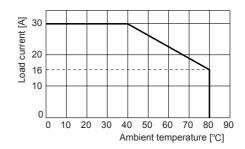
© SRH1-1415/1415R/2415-N



© SRH1-1420/1420R/2420-N



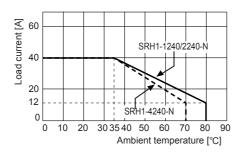
© SRH1-1430/1430R/2430-N



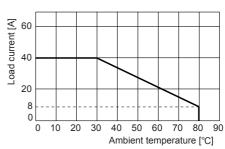
I-20 Autonics

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

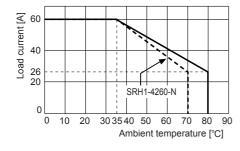
© SRH1-1240/2240/4240-N



© SRH1-1440/1440R/2440-N



SRH1-1260/1460/1460R-N SRH1-2260/2460/4260-N



△ Since effectiveness of the heat radiation is decreased when multiple SSRs are installed closely, please supply less than 50% of the rated load current.

XAbove SSR derating curves obtained approval from the UL certification authority.

■ Proper Usage

⚠ Cautions during use

- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. 4-30VDC, 24VAC signal input should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Install the unit in the well ventilated place.
- 3. Ground to the heat sink, panel, or DIN rail. Failure to follow this instruction may result in electric shock.
- 4. Ground to the panel. Failure to follow this instruction may result in electric shock.
- 5. While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- 6. In order to protect the product from the short-circuit current of the load, use rapid fuse of which l²t is under the 1/2 of SSR l²t. When short-circuited, replace the fuse to those of same specification with the used rapid fuse.
- Install dummy resistance in parallel with the load, to keep the sum of current flowing in the load and dummy resistance being over SSR minimum load current.
- 8. When using random turn-on model for phase control, install noise filter between the load and the power of the load.
- 9. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- 10. This unit may be used in the following environments.
 - ① Indoors (in the environment condition rated in 'Specifications')
 - ② Altitude max. 2,000m
 - ③ Pollution degree 2
 - 4 Installation category III

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity

(E) Pressure Sensors

(F) Rotary

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers



Counters

() imers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

>) splay

D) ensor

(P) Switching Mode Powe Supplies

Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

> T) Software

Autonics I-21

Single-Phase, Integrated Heatsink Type SSR [Current Input Type]

■ Model

Model	Rated input current		Rated load voltage	Model			Rated load voltage
SRH1-A220-N		20A		SRH1-A420-N		20A	
SRH1-A230-N	4-20mA	30A	100-240VAC	SRH1-A430-N	4-20mA	30A	200-480VAC
SRH1-A260-N		60A		SRH1-A460-N		60A	

Specifications

O Input

Rated input current	4-20mA
Max. allowable input current	50mA
Pick-up current	Min. 4.2mA
Static off current	Max. 4.0mA
Power factor	Min. 0.9 (max. 25° of difference between voltage phase and current phase)
Start-up time	60Hz: 200ms, 50Hz: 250ms
Operation time	60Hz: 16.6ms, 50Hz:20ms
Operation mode ^{*1}	Phase control (phase equality division type, power equality division type) Cycle control (fixed cycle, variable cycle)

X1: You can change operation mode by jumper pin. Default is Phase control (Power equality division type).

Output

Rated load voltage range		100-240VACrms~ (50/60Hz)			200-480VACrms~ (50/60Hz)			
Allowable load	l voltage range	90-264VACrms~ (50/60Hz)			200-528VACrms~ (50/60Hz)			
Rated load current	Resistive load (AC-51) ^{×1}	20Arms	30Arms	60Arms	20Arms	30Arms	60Arms	
Min. load curr	ent	0.5Arms			0.5Arms			
Max. 1 cycle surge current (60Hz)		300A	500A	1000A	300A	500A	1000A	
Max. non-repetitive surge current (I²t, t=8.3ms)		350A ² s	1000A ² s	4000A ² s	350A ² s	1000A ² s	4000A ² s	
Peak voltage (r	non-repetitive)	600V			1000V			
Leakage current (Ta=25°C)		Max. 10mArms (240VAC~/60Hz)			Max. 10mArms (480VAC~/60Hz)			
Output on voltage drop[Vpk] (Max. load current)		Max. 1.6V						
Static off-state	e dv/dt	500V/μs	500V/μs					

X1: AC-51 are utilization category at IEC60947-4-3.

General specifications

Phase control					
(phase equality division type)		5 to 99%			
Phase control		10 to 99%			
(power equalit	y division type)	10 10 35 %			
Frequency rea	ading function	Yes			
Dielectric strei	ngth (Vrms)	4000VAC 50/60Hz for 1 min (input-output, input/output-case)			
Insulation resi	stance	Over 100MΩ (at 500VDC megger)			
Indicator		Input indicator: green LED			
Vibration		0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour			
	Ambient temp.	-20 to 70°C, storage: -20 to 100°C			
Environment	, and one tomp.	(The rated load current capacity is different depending on ambient temperature. Refer to 🔳 SSR Derating Curve'.)			
	Ambient humi.	45 to 85%RH, storage: 45 to 85%RH			
Input terminal	connection	Min. 1×0.5mm² (1×AWG20), max. 1×16mm² (1×AWG6) or 2×1.5mm² (2×AWG16)			
Output termina	al connection	Min. 1×1.5mm ² (1×AWG16), max. 1×16mm ² (1×AWG6) or 2×6mm ² (2×AWG10)			
Output terriiiri	ai connection	XUse wires compliant with load current capacity to connect to the terminal.			
Input terminal fixed torque		0.75 to 0.95N·m			
Output terminal fixed torque		1.6 to 2.2N·m			
Approval		20 ∠PR 3 ∋)			
Unit weight		Rated load current 20A/30A: Approx. 410g Rated load current 60A: Approx. 680g			
		Trated load current out. Approx. outg			

XEnvironment resistance is rated at no freezing or condensation.

I-22 Autonics

[%]For wiring the terminal, round terminal must be used.

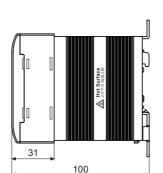
Single-Phase, Integrated Heatsink Type SSR [Current Input Type]



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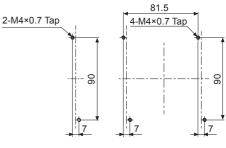
4.5

90



O Hole cut-out for mounting on panel

• Rated load current 20A/30A • Rated load current 60A



 $\%\mbox{Screw}$ tightening torque for mounting: 1.8 to 2.5N·m

• Rated load current 60A

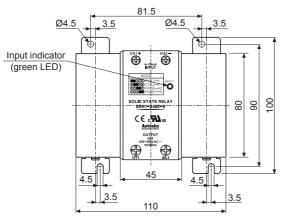
(1)

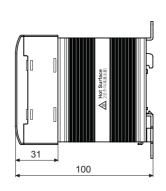
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Input indicator

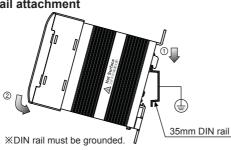
(green LED)





O DIN rail mounting

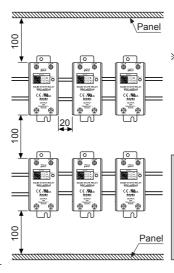
• DIN rail attachment



• DIN rail detachment

SERVICE OF THE PROPERTY OF THE PROPERTY

Spacing



When installing multiple SSRs, please keep space between SSRs for heat radiation. When installing SSRs horizontally (input part and output part on the same height), please supply less than 50% of the rated load current.

High temperature caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.

(unit: mm)
(A)
Photoelectric
Sensors

(B) Fiber

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure

Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

> o)) ensor entrollers

(P) Switching Mode Power Supplies

Supplies
(Q)
Stepper Motors

(R) Graphic/ Logic Panels

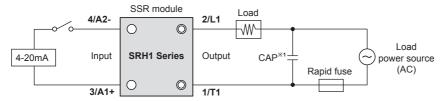
S) ield letwork

T) ioftware

Autonics 1-23

SRH1 Series

Connections



X1: When connecting noise filter and capacitor, it is appropriate for EMC.

CAP: Rated load voltage 100-240VAC → 1uF/250VAC

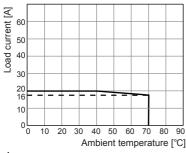
Rated load voltage 200-480VAC → 0.47uF/500VAC

*Use terminals of size specified below.

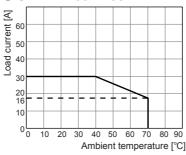
Terminal type		Input	Output
□ ↓a b	а	Min. 3.5mm	Min. 5.0mm
<round></round>	b	Max. 7.0mm	Max. 12.0mm

SSR Derating Curve

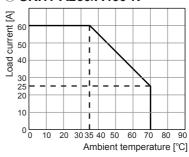
© SRH1-A220/A420-N



SRH1-A230/A430-N



SRH1-A260/A460-N



XAbove SSR derating curves obtained approval from the UL certification authority.

Operation Setting

• Detach front cover

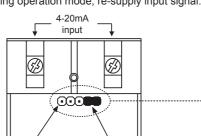
Press front cover connection 4 parts at right and left side with (-) driver, and front cover is detached.

**Refere detaching front cover, you must cut off load.

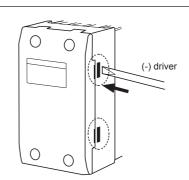
• Jumper pin setting

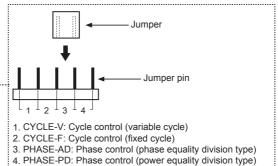
Operation mode is decided by jumper position. After changing operation mode, re-supply input signal.

Jumper pin



Jumper





(factory default)

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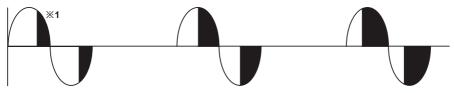
Single-Phase, Integrated Heatsink Type SSR [Current Input Type]

Operation Mode

O Phase control

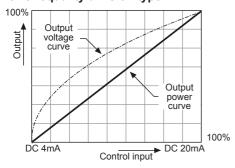
Output waveform of phase control

• When control input signal is 25% • When control input signal is 50% • When control input signal is 75%



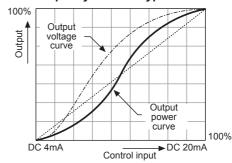
X1: The black parts of output waveform are output on the load.

• Power equality division type



Controls output power which is proportional to control input (4-20mA) level.

• Phase equality division type



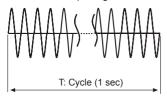
Controls phase angle which is proportional control input (4-20mA) level.

O Cycle control

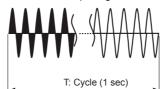
• Fixed cycle

Controls continuously the number of full cycle which is supplied to load every 1 sec by being proportional to control input (4-20mA).

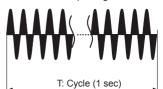
· When control input signal is 0%



· When control input signal is 50%



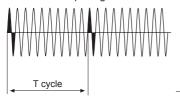
When control input signal is 100%



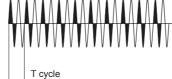
Variable cycle

Controls fast and accurately the subject with optimized the number of AC voltage cycle which is supplied to load by being proportional to control input (4-20mA).

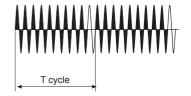
· When control input signal is 10%



· When control input signal is 50%



When control input signal is 90%



(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

> (F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

Temperature Controllers



Counters

_)

(M) Tacho / Speed / Pulse Meters

N) Display Jnits

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

Autonics I-25

SRH1 Series

Proper Usage

- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. Install the unit in the well ventilated place.
- 3. Ground to the heat sink, panel, or DIN rail. Failure to follow this instruction may result in electric shock.
- 4. While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- 5. In order to protect the product from the short-circuit current of the load, use rapid fuse of which I²t is under the 1/2 of SSR I²t. When short-circuited, replace the fuse to those of same specification with the used rapid fuse.
- 6. Install dummy resistance in parallel with the load, to keep the sum of current flowing in the load and dummy resistance being over SSR minimum load current.
- 7. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- 8. This unit may be used in the following environments.
 - ① Indoors (in the environment condition rated in 'Specifications')
 - ② Altitude max. 2,000m
 - 3 Pollution degree 2
 - 4 Installation category III

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